

AMENDMENT TO THE CLAIMS

Claims 1-6 (Cancelled)

7.(New) A component placement recognition mark recognizing device for recognizing recognition marks for component placement that are provided corresponding to component placement positions where components are to be placed in a plurality of partition areas on a board, the component placement recognition mark recognizing device comprising:

a recognizing unit for recognizing the recognition marks straightly disposed in the plurality of areas, and

a moving device for running the recognizing unit at a generally uniform velocity in a deposition direction in which the recognition marks are straightly disposed,

wherein the recognition marks are recognized with use of the recognizing unit while the recognizing unit is run by the moving device.

8.(New) A component placement recognition mark recognizing device as claimed in claim 7, wherein the velocity at which the recognizing unit is run by the moving device is a velocity obtained from a distance between adjoining recognition marks divided by time required for capture of an image of the recognition mark.

9.(New) A component placement recognition mark recognizing device as claimed in claim 7, wherein the plurality of areas are made into one block and wherein the recognition marks for component placement that are located in a confronting pair of corners of the block and in different areas are recognized with use of the recognizing unit.

10.(New) A component placement recognition mark recognizing method for recognizing recognition marks for component placement that are provided corresponding to component

placement positions where components are to be placed in a plurality of partition areas on a board,

the component placement recognition mark recognizing method comprising: respectively recognizing the recognition marks straightly disposed in the plurality of areas with use of a recognizing unit while the recognizing unit is run at a generally uniform velocity in a deposition direction in which the recognition marks are straightly disposed.

11.(New) A component placement recognition mark recognizing method as claimed in claim 10, wherein the velocity at which the recognizing unit is run by the moving device is a velocity obtained from a distance between adjoining recognition marks divided by time required for capture of an image of the recognition mark.

12.(New) A component placement recognition mark recognizing method as claimed in claim 10, wherein the recognition marks for component placement that are located in a confronting pair of corners of one block composed of the plurality of areas and positioned in different areas are recognized with use of the recognizing unit.

13.(New) A component placement recognition mark recognizing device as claimed in claim 8, wherein the plurality of areas are made into one block and wherein the recognition marks for component placement that are located in a confronting pair of corners of the block and in different areas are recognized with use of the recognizing unit.

14.(New) A component placement recognition mark recognizing method as claimed in claim 11, wherein the recognition marks for component placement that are located in a confronting pair of corners of one block composed of the plurality of areas and positioned in different areas are recognized with use of the recognizing unit.